

## Some Helpful and Not-So-Helpful Equations

- E1.  $E = mc^2$
- E2.  $\frac{{}^i d}{dt}(\cdot) = \frac{{}^b d}{dt}(\cdot) + \vec{\omega}^{bi} \times (\cdot)$
- E3.  $\frac{{}^i d^2}{dt^2}(\cdot) = \frac{{}^b d^2}{dt^2}(\cdot) + \frac{{}^b d}{dt}(\vec{\omega}^{bi}) \times (\cdot) + 2\vec{\omega}^{bi} \times \frac{{}^b d}{dt}(\cdot) + \vec{\omega}^{bi} \times [\vec{\omega}^{bi} \times (\cdot)]$
- E4.  $\vec{F}_e = m \frac{{}^i d^2}{dt^2} \vec{r}_c$
- E5.  $H^b = I^b \omega^{bi} + m \tilde{r}^b v^b$
- E6.  $\vec{\omega}^{bi} = \omega_1 \vec{b}_1 + \omega_2 \vec{b}_2 + \omega_3 \vec{b}_3$
- E7.  $I^a = R^{ba} I^b R^{ab}$
- E8.  $I^b = - \int_m \tilde{r}^b \tilde{r}^b \partial m$
- E9.  $I = \int \begin{bmatrix} y^2 + z^2 & -xy & -xz \\ -xy & x^2 + z^2 & -yz \\ -xz & -yz & x^2 + y^2 \end{bmatrix} \partial m$
- E10.  $R^{bi} = R_3(-\psi) R_2(-\theta) R_1(-\phi)$
- E11.  $C_{m_\alpha} = C_{L_{\alpha w}} \left( \frac{x_{cg}}{\bar{c}} - \frac{x_{ac}}{\bar{c}} \right) + C_{m_{\alpha f}} - \eta V_H C_{L_{\alpha t}} \left( 1 - \frac{d\varepsilon}{d\alpha} \right)$
- E12.  $\frac{x_{NP}}{\bar{c}} = \frac{x_{ac}}{\bar{c}} - \frac{C_{m_{\alpha f}}}{C_{L_{\alpha w}}} + \eta V_H \frac{C_{L_{\alpha t}}}{C_{L_{\alpha w}}} \left( 1 - \frac{d\varepsilon}{d\alpha} \right)$
- E13.  $C_{L_\alpha} = \frac{C_{l_\alpha}}{1 + C_{l_\alpha} / (\pi AR)}$
- E14.  $f = \left( 1 - \frac{C_{L_{\delta e}} C_{h_{\alpha t}}}{C_{L_{\alpha t}} C_{h_{\delta e}}} \right)$
- E15.  $L = I_x \dot{p} - I_{zx} \dot{r} + qr(I_z - I_y) - I_{zx} pq$   
 $M = I_y \dot{q} + rp(I_x - I_z) + I_{zx}(p^2 - r^2)$   
 $N = I_z \dot{r} - I_{zx} \dot{p} + pq(I_y - I_x) + I_{zx} qr$   
 $X - mg \sin \theta = m(\dot{u} + qw - rv)$
- E16.  $Y + mg \cos \theta \sin \phi = m(\dot{v} + ru - pw)$   
 $Z + mg \cos \theta \cos \phi = m(\dot{w} + pv - qu)$
- E17.  $E = \frac{v^2}{2} - \frac{\mu}{r}$
- E18.  $\frac{r}{R} \approx \left( \frac{m}{M} \right)^{2/5}$